PUBLICLY AVAILABLE SPECIFICATION

ISO/PAS 21448

First edition 2019-01

Road vehicles — Safety of the intended functionality

Véhicules routiers - Sécurité de la fonction attendue



Reference number ISO/PAS 21448:2019(E)



COPYRIGHT PROTECTED DOCUMENT

© ISO 2019

All rights reserved. Unless otherwise specified, or required in the context of its implementation, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office CP 401 • Ch. de Blandonnet 8 CH-1214 Vernier, Geneva Phone: +41 22 749 01 11 Fax: +41 22 749 09 47 Email: copyright@iso.org Website: www.iso.org

Published in Switzerland

Cor	Contents				
Fore	word	v			
Intro	oduction	vi			
1	Scope	1			
2	Normative references				
3	Terms and definitions				
4	Overview of this document's activities in the development process				
5	Functional and system specification (intended functionality content)				
	5.1 Objectives	11			
	5.2 Functional description5.3 Consideration on system design and architecture				
6					
	Identification and Evaluation of hazards caused by the intended functionality 6.1 Objectives				
	6.2 Hazard identification	14			
	6.3 Hazard analysis				
	6.5 Specification of a validation target				
7	Identification and Evaluation of triggering events				
	7.1 Objectives	17			
	7.2 Analysis of triggering events 7.2.1 Triggering events related to algorithms				
	7.2.1 Triggering events related to algorithms				
	7.3 Acceptability of the triggering events				
8	Functional modifications to reduce SOTIF related risks				
	8.1 Objectives				
	8.2 General 8.3 Measures to improve the SOTIF				
	8.4 Updating the system specification				
9	Definition of the verification and validation strategy				
	9.1 Objectives				
4.0	9.2 Planning and specification of integration and testing				
10	Verification of the SOTIF (Area 2)				
	10.2 Sensor verification				
	10.3 Decision algorithm verification				
	10.4 Actuation verification				
11	Validation of the SOTIF (Area 3)				
	11.1 Objectives				
	11.2 Evaluation of residual risk				
	11.3 Validation test parameters				
12	Methodology and criteria for SOTIF release 12.1 Objectives	27			
	12.2 Methodology for evaluating SOTIF for release				
	12.3 Criteria for SOTIF release	28			
Anne	ex A (informative) Examples of the application of SOTIF activities	30			
Anne	ex B (informative) Example for definition and validation of an acceptable false alarm rate in AEB systems	33			
Δnna	ex C (informative) Validation of SOTIF annlicable systems	41			

ISO/PAS 21448:2019(E)

Annex D (informative) Automotive perception systems verification and validation	43
Annex E (informative) Method for deriving SOTIF misuse scenarios	46
Annex F (informative) Example construction of scenario for SOTIF safety analysis method	49
Annex G (informative) Implications for off-line training	52
Bibliography	54

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 22, *Road vehicles*, Subcommittee SC 32, *Electrical and electronic components and general system aspects*.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

The safety of road vehicles during their operation phase is of paramount concern for the road vehicles industry. Recent years have seen a large increase in the number of advanced functionalities included in vehicles. These rely on sensing, processing of complex algorithms and actuation implemented by electrical and/or electronic (E/E) systems.

An acceptable level of safety for road vehicles requires the avoidance of unreasonable risk caused by every hazard associated with the intended functionality and its implementation, especially those not due to failures, e.g. due to performance limitations. ISO 26262-1 defines the vehicle safety as the absence of unreasonable risks that arise from malfunctions of the E/E system. ISO 26262-3 specifies a Hazard Analysis and Risk Assessment to determine vehicle level hazards. This evaluates the potential risks due to malfunctioning behaviour of the item and enables the definition of top-level safety requirements, i.e. the safety goals, necessary to mitigate the risks. The other parts of the ISO 26262 series provide requirements and recommendations to avoid and control random hardware failures and systematic failures that could violate safety goals.

For some systems, which rely on sensing the external or internal environment, there can be potentially hazardous behaviour caused by the intended functionality or performance limitation of a system that is free from the faults addressed in the ISO 26262 series. Examples of such limitations include:

- The inability of the function to correctly comprehend the situation and operate safely; this also includes functions that use machine learning algorithms;
- Insufficient robustness of the function with respect to sensor input variations or diverse environmental conditions.

The absence of unreasonable risk due to these potentially hazardous behaviours related to such limitations is defined as the safety of the intended functionality (SOTIF). Functional safety (addressed by the ISO 26262 series) and SOTIF are distinct and complementary aspects of safety.

To address the SOTIF, activities are implemented during the following phases:

- Measures in the design phase;
 - EXAMPLE Requirement on sensor performance.
- Measures in the verification phase;
 - EXAMPLE Technical Reviews, test cases with a high coverage of relevant scenarios, injection of potential triggering events, in the loop testing (e.g. SIL/HIL/MIL) of selected SOTIF are relevant use cases.
- Measures in the Validation phase.
 - EXAMPLE Long term vehicle test, simulations.

A proper understanding of the function by the user, its behaviour and its limitations (including the human/machine interface) is the key to ensuring safety.

In many instances, a triggering event is necessary to cause a potentially hazardous behaviour; hence the importance of analysing hazards in the context of particular use cases.

In this document the hazards caused by a potentially hazardous system behaviour, due to a triggering event, are considered both for use cases when the vehicle is correctly used and for use cases when it is incorrectly used in a reasonably foreseeable way (this excludes intentional alterations made to the system's operation).

EXAMPLE Lack of driver attention while using a level 2 driving automation.

In addition, reasonably foreseeable misuse, which could lead directly to potentially hazardous system behaviour, is also considered as a possible triggering event.

A successful attack exploiting vehicle security vulnerabilities can also have very serious consequences (i.e. data or identity theft, privacy violation, etc.). Although security risks can also lead to potentially hazardous behaviour that needs to be addressed, security is not addressed by this document.

It is assumed that the E/E random hardware faults and systematic faults of the E/E system are addressed using the ISO 26262 series. The activities mentioned in this document are complementary to those given in the ISO 26262 series.

<u>Table 1</u> illustrates how the possible causes of hazardous event map to existing standards.

Table 1 — Overview of safety relevant topics addressed by different ISO standards

Source	Cause of hazardous event	Within scope of			
	E/E System failures	ISO 26262 series			
	Performance limitations or insufficient situational awareness, with or without reasonably foreseeable misuse	ISO/PAS 21448			
Contain		ISO/PAS 21448			
System		ISO 26262 series			
		European statement of principal on the design of human-ma-chine-interface			
	Hazards caused by the system technology	Specific standards			
	successful attack exploiting vehicle security vulnerabilities	ISO 21434 ^a or SAE J3061			
External factor	Impact from active Infrastructure and/or vehicle to vehicle communication, external devices and cloud services.	ISO 20077 series; ISO 26262 series			
	Impact from car surroundings (other users, "passive" infrastructure, environmental conditions: weather, Electro-Magnetic Interference)	ISO/PAS 21448			
		ISO 26262 series			
^a Under preparation. Stage at the time of publication: ISO/SAE CD 21434.					

NOTE Options for automated driving level definitions (from NHTSA, SAE and OICA, etc.) are discussed in the ITS-Informal Group ECE/TRANS/WP29.